Bilevel Programming and MPCC : Connections and Counterexamples Joydeep Dutta Dept of Economic Sciences, IIT Kanpur

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Bilevel Programming Problem

$$\min_{x} F(x, y), \quad \text{ subject to } \quad x \in X, y \in S(x),$$

where for each $x \in X$ the set S(x) is given as

$$S(x) = \operatorname{argmin}_y \{ f(x, y) : y \in K(x) \},$$

where $F : \mathbb{R}^n \times \mathbb{R}^m \to \mathbb{R}$, $f : \mathbb{R}^n \times \mathbb{R}^m \to \mathbb{R}$ and K(x) is a closed convex set in \mathbb{R}^m depending on $x \in X$.

In our presentation we shall restrict ourselves to the case where $X = \mathbb{R}^n$ im most situations. The set $\mathcal{K}(x)$ will often be given as

$$\mathcal{K}(x) = \{y \in \mathbb{R}^m : g_i(x, y) \leq 0, i = 1, \dots, k\},\$$

here $y \mapsto g_i(x, y)$ is convex for each *i*.

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Optimistic and Pessimistic Formulation

The optimistic formulation is given as follows : Consider that $S(x) \neq \emptyset$ for each x and define the function

$$\varphi_0(x) = \min_{y \in S(x)} F(x, y).$$

Then the *optimistic problem* is to minimize φ_0 over x. We shall refer to the optimistic problems as (BP_o) .

The pessimistic formulation is given as follows : Let us define the function

$$\varphi_p(x) = \max_{y \in S(x)} F(x, y).$$

Thus the pessimistic bilevel problem consist of minimizing φ_p over \mathbb{R}^n . Note that the pessimistic formulation of a bilevel problem is viewed as one where the follower does not cooperate with the leader.

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This optimistic bilevel programming problem which is denoted as (OBP) is given as

$$\min_{x,y} F(x,y), \quad \text{subject to} \quad y \in S(x).$$

Most researchers speak of this formulation as the bilevel programming. How is this problem related to the original optimistic formulation. How is (BP_o) is related to (OBP).

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Relation between optimistic formulation and OBP

Result 1 :

Let \bar{x} be the local solution of the optimistic formulation (BP_o) . Then for any $\bar{y} \in S(\bar{x})$, the vector (\bar{x}, \bar{y}) is a local minimum of (OBP) if \bar{y} be such that $\varphi_o(\bar{x}) = F(\bar{x}, \bar{y})$.

Result 2 : Let (\bar{x}, \bar{y}) be the global minimizer of (OBP). Then \bar{x} is a global minimizer of the problem (BP_o) .

Result 3 : Let (\bar{x}, \bar{y}) be the global minimizer of (OBP). Then \bar{x} is a global minimizer of the problem (BP_o) .

Let the set K(x) be defined by convex inequalities. The KKT reformulation of (OBP) is given below and is called (OBP-KKT)

 $\min_{x,y} F(x,y), \quad \text{subject to} \quad x \in X, \nabla L(x,y,u) = 0, \quad u \ge 0, u^T g(x,y) = 0,$

where L(x, y, u) is the Lagrangian function associated with the lower-level problem. The set of Lagrangian multipliers of the lower-level problem is given as

$$\Lambda(x,y) = \{ u : \nabla L(x,y,u) = 0, \quad u \ge 0, u^T g(x,y) = 0 \}$$

The set set X is often \mathbb{R}^n .

Result 4 : Let (\bar{x}, \bar{y}) be a global minimizer of (OBP) and the Slater CQ holds for the lower-level problem at $x = \bar{x}$. Then for any $\bar{u} \in \Lambda(\bar{x}, \bar{y})$, we have that $(\bar{x}, \bar{y}, \bar{u})$ is a solution of (OBP-KKT).

Result 5 : Let $(\bar{x}, \bar{y}, \bar{u})$ be the global minimizer of (OBP-KKT). Let us assume that the Slater constraint qualification holds true for the lower-level problem for each $x \in X$. Then (\bar{x}, \bar{y}) solves (OBP).

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Example : Global Case

Consider the following (OBP) in \mathbb{R}^2 .

$$\min_{x,y}(x-1)^2+y^2, \quad x\in\mathbb{R}, y\in S(x),$$

$$S(x) = \operatorname{argmin}_{y} \{ x^2 y : y^2 \le 0 \}$$

Solution of (SBP) : $(\bar{x}, \bar{y}) = (0, 0)$. Associated MPCC problem

 $\min_{x,y,\lambda}(x-1)^2+y^2;$ subject to $x^2+2\lambda y=0, \quad \lambda\geq 0, \quad y^2\leq 0, \lambda y^2=0.$

All feasible points of the MPCC is of the form $(0, 0, \lambda)$ thus by solving the MPCC we cannot solve the bilevel problem in the context of global minimizers.

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Consider the following (OBP) in the \mathbb{R}^2 .

$$\min_{x,y}(x-1)^2+(y-1)^2, \quad ext{subject to} \quad x\in\mathbb{R}, y\in\mathcal{S}(x),$$

where

$$S(x) = argmin_y \{-y : x + y \le 1, -x + y \le 1\}.$$

The problem (OBP) has a unique global minimizer $(\bar{x}, \bar{y}) = (0.5, 0.5)$ and there are no local minimizers.

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Example : Contd

The corresponding MPCC is given as

$$\min_{x,y,\lambda} (x-1)^2 + (y-1)^2,$$

subject to

$$-1 + u_1 + u_2 = 0, u_1 \ge 0, u_2 \ge 0$$
$$u_1(x + y - 1) = 0$$
$$u_2(x + y - 1) = 0$$
$$x + y - \le 0$$
$$-x + y - 1 \le 0.$$

For example $(x^*, y^*, u_1^*, u_2^*) = (0, 1, 0, 1)$ is a local solution of MPCC but (0, 1) is not a local solution of (OBP).

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Let \bar{x} be a point where Slater condition holds for the lower-level problem. Let \bar{y} be a solution of the lower-level problem corresponding to \bar{x} . For each $\bar{u} \in \Lambda(\bar{x}, \bar{y})$ the point $(\bar{x}, \bar{y}, \bar{u})$ is a local minimizer of (OBP). Then (\bar{x}, \bar{y}) is a local minimizer of (OBP).

Simple Bilevel Programming Problem

Let us consider the following Simple Bilevel Programming (SBP) problem

$$\begin{array}{l} \text{minimize } f(x) \\ \text{subject to} \\ x \in \operatorname{argmin}\{h(x) : g(x) \leq 0\}. \end{array} \tag{1}$$

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Now the question is if the lower level problem i.e.

minimize h(x)subject to $g(x) \le 0.$

can be replaced by its Karush Kuhn Tucker conditions?

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The answer is yes if the Slater's CQ condition holds for the lower level problem.

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If the lower level problem of the SBP (1) is replaced by the KKT conditions then we get the following simple MPCC problem

minimize
$$f(x)$$

subject to
 $\nabla h(x) + \lambda^t \nabla g(x) = 0$
 $g(x) \le 0$
 $\lambda \ge 0$
 $\lambda^t g(x) = 0.$
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For any $x \in \mathbb{R}^n$ such that $g(x) \leq 0$, Let us define

$$\Lambda(x) := \{\lambda \ge 0 : \nabla h(x) + \lambda^t \nabla g(x) = 0, \lambda^t g(x) = 0\}$$

Then (x, λ) is a feasible point of the problem (2).

Theorem

Let \bar{x} is a global optimal solution of the simple bilevel programming problem and assume that the lower level problem satisfies the Slater's CQ condition i.e. $\exists x \in \mathbb{R}^n$ such that g(x) < 0. Then for any $\lambda \in \Lambda(\bar{x})$, the point (\bar{x}, λ) is a global optimal solution of the corresponding MPCC Problem.

Theorem

Let the Slater's condition holds for the lower level problem (2) of the SBP . Then $(\bar{x}, \bar{\lambda})$ is a local solution of the MPCC problem implies that \bar{x} is a global solution of the SBP problem.

Corollary

Let the Slater's condition holds for the lower level problem (2) of the SBP . Then $(\bar{x}, \bar{\lambda})$ is a local solution of the corresponding MPCC problem implies that $(\bar{x}, \bar{\lambda})$ is a global solution of the same.

Example

Slater's condition holds and the solution of SBP and MPCC are same. Let

$$f(x) = (x - \frac{1}{2})^2$$

$$h(x) = \begin{cases} 0 & \text{if } 0 \le x \le 1 \\ 1 & \text{if } x > 1 \end{cases}$$

$$g_1(x) = -x$$

$$g_2(x) = x - 3$$

Then Slater's condition holds as $g_1(2) < 0$ and $g_2(2) < 0$. Here the feasible set for the MPCC problem is

$$\{(x, \lambda_1, \lambda_2) : 0 \le x \le 1, \lambda_1 = 0, \lambda_2 = 0\}$$

Hence the global optimal solution for the MPCC problem is $x = \frac{1}{2}$ with optimal value $f(\frac{1}{2}) = 0$. The feasible set of the SBP problem is

$$\operatorname{argmin}\{h(x): 0 \le x \le 3\} = \{x: 0 \le x \le 1\}$$

Therefore the global solution of the SBP problem is same as the MPCC i.e. $x = \frac{1}{2}$.

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The SBP and MPCC problems are different in general if the Slater's condition is not satisfied. Next we present some examples to show how they are different.

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Example

SBP has unique solution but corresponding MPCC is not feasible (Slater's condition is not satisfied).

Let

$$f(x_1, x_2) = x_1 + x_2$$

$$h(x_1, x_2) = x_1$$

$$g_1(x_1, x_2) = x_1^2 - x_2$$

$$g_2(x_1, x_2) = x_2$$

Clearly, $g_1(x_1) \leq 0$ and $g_2(x_1, x_2) \leq 0$ together imply that $x_1 = 0 = x_2$. Which implies that Slater's condition fails for the lower level problem of the SBP.

Now, the feasible set for the SBP problem is

$$\operatorname{argmin}\{h(x_1, x_2) : x_1 = 0 = x_2\} = \{(0, 0)\}\$$

Therefore, (0,0) is the solution of the SBP problem. But for $x_1 = 0 = x_2$, there does not exists $\lambda_1 \ge 0$ and $\lambda_2 \ge 0$ such that

$$\nabla h(x_1, x_2) + \lambda_1 \nabla g_1(x_1, x_2) + \lambda_2 \nabla g_2(x_1, x_2) = 0$$

Therefore the MPCC problem is not feasible even when the SBP has unique solution in case of the failure of Slater's condition.

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SBP and simple MPCC

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Example

SBP and the corresponding MPCC both are feasible but have different solution sets (Slater's condition is not satisfied). Let

$$f(x, y) = (x - 1)^{2} + y^{2}$$

$$h(x, y) = x^{2}y$$

$$g_{1}(x, y) = y^{2}$$

$$g_{2}(x, y) = -x$$

Now, $g_1(x,y) \leq 0$ and $g_2(x,y) \leq 0$ together implies that

 $x \ge 0$ and y = 0.

Therefore,

$$\operatorname{argmin}\{h(x, y) : x \ge 0, y = 0\} = \{(x, 0) : x \ge 0\}$$

Hence, (1,0) is the solution of the SBP problem with optimal value f(1,0) = 0.

Now for the MPCC problem and $x \ge 0, y = 0$

$$\nabla h(x,y) + \lambda_1 \nabla g_1(x,y) + \lambda_2 \nabla g_2(x,y) = 0$$

holds true if $x = 0, y = 0, \lambda_1 \ge 0, \lambda_2 = 0$. Therefore, x = 0, y = 0 is the optimal solution for the MPCC problem with optimal value f(0,0) = 1 which is different from the SBP problem.

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References

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