

Lecture 14: September 23

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This lecture's notes illustrate some uses of various \LaTeX macros. Take a look at this and imitate.

14.1 Dynamic Games

The assumption in games studied till now was that all players play simultaneously. We now allow players to play possibly sequentially (some may play sequentially, some simultaneously). Players may play after one another or players may even play multiple times. All of this will be allowed.

Example: Two players have coins and they have to put the coin in either heads or tails facing upwards.

	H	T
H	(+1, -1)	(-1, +1)
T	(-1, +1)	(+1, -1)

If the game is simultaneous, none of the players has the option of seeing what the other player has played and then decide his own strategy. Only if we allow a player certain information before he picks his strategy, only then will the game be fundamentally different from a simultaneous game.

Example: *Cournot Game* - Two firms P_1 and P_2 , producing q_1 and q_2 quantities of an item respectively. For some constant c , we have:

$$U_i(q_1, q_2) = [1 - (q_1 + q_2)]q_i - cq_i$$

Where U_i denotes the payoff of P_i .

Suppose P_2 observes the action of P_1 . Let $Q_1 = \text{space of } q_1$, $Q_2 = \text{space of } q_2$.

A strategy for P_2 is a function $\gamma^2 : Q_1 \rightarrow Q_2$; whereas, a strategy for P_1 is just a quantity q_1 , or equivalently Q_1 valued functions that are constants.

Can we predict what gets played? It makes sense to think that given P_1 's response q_1 , P_2 's response will be the best response possible (the one which gives the maximum payoff to P_2 given that q_1 was played). Let $R_i(\cdot)$ denote P_i 's best response strategy, then assuming that $R(\cdot)$ is a single value map:

$$\gamma_2^*(q_1) = R_2(q_1) = \operatorname{argmax}_{q_2'} U_2(q_1, q_2')$$

$$q_1^* = \operatorname{argmax}_{q_1} U_1(q_1, R_2(q_1))$$

Thus, the game can be thought of as a static game in the space of functions.

14.2 Nash Equilibrium of a Dynamic Game

Definition 14.1 *Nash equilibrium: Functions γ_1^*, γ_2^* such that*

$$U_1(\gamma_1^*, \gamma_2^*) \geq U_1(\gamma_1, \gamma_2^*) \quad \forall \text{ constant } \gamma_1 \quad (14.1)$$

$$U_2(\gamma_1^*, \gamma_2^*) \geq U_2(\gamma_1^*, \gamma_2) \quad \forall \text{ functions } \gamma_2 \text{ of } q_1 \quad (14.2)$$

We now show that $\gamma_1^* = q_1^*, \gamma_2^* = R_2$ is a Nash equilibrium of the dynamic game:

$$\begin{aligned} U_1(q_1^*, R_2(q_1^*)) &= \max_{\gamma_1} U_1(\gamma_1, \gamma_2^*(\gamma_1)) \\ &= \max_{q_1} U_1(q_1, \gamma_2^*(q_1)) \\ &= \max_{q_1} U_1(q_1, R_2(q_1)) \end{aligned}$$

And,

$$\begin{aligned} U_2(\gamma_1^*, \gamma_2^*) &= \max_{\gamma_2} U_2(q_1^*, \gamma_2(q_1^*)) \\ &= U_2(q_1^*, R_2(q_1^*)) \end{aligned}$$

14.2.1 Another Nash Equilibrium

If (q_1^{**}, q_2^{**}) is a static Nash Equilibrium of the game, then the equivalent dynamic strategies are $(\gamma_1^{**}, \gamma_2^{**}) \equiv (q_1^{**}, q_2^{**})$. It is worthwhile to note that in this case, P_2 's strategy is a constant (independent of what P_1 plays). P_2 though blessed with the information of what P_1 plays, decides to ignore that.

We now try to show that (q_1^{**}, q_2^{**}) is also the Nash equilibrium of the dynamic game. Consider:

$$\begin{aligned} U_1(\gamma_1^{**}, \gamma_2^{**}) &= U_1(q_1^{**}, q_2^{**}) \\ &= \max_{q_1} U_1(q_1, q_2^{**}) \end{aligned}$$

where the second equality holds due to the definition of a static Nash equilibrium strategy.

$$\begin{aligned} &= \max_{\gamma_1} U_1(\gamma_1, \gamma_2^{**}) \\ \therefore U_1(\gamma_1^{**}, \gamma_2^{**}) &\geq U_1(\gamma_1, \gamma_2^{**}) \quad \forall \text{ constant } \gamma_1 \end{aligned} \quad (14.3)$$

which is a reminiscent of Eq. (14.1)

Now consider:

$$\begin{aligned} U_2(\gamma_1^{**}, \gamma_2^{**}) &= U_2(q_1^{**}, q_2^{**}) \\ &= \max_{q_2} U_2(q_1^{**}, q_2) \\ &= \max_{\gamma_2} U_2(q_1^{**}, \gamma_2(q_1^{**})) \end{aligned} \quad (14.4)$$

Any function γ_2 that satisfies $\gamma_2(q_1^{**}) = q_2^{**} (= R_2(q_1^{**}))$ will maximize $U_2(q_1^{**}, \gamma_2(q_1^{**}))$. Thus, the function $\gamma_2 \equiv q_2^{**}$ is also a maximizer. This proves the truth of the last equality – which is equivalent to Eq. (14.2).

Hence, by Eq. (14.3), (14.4), we have shown that (q_1^{**}, q_2^{**}) is a Nash equilibrium of the dynamic game. Note that, however every function which satisfies $\gamma_2(q_1^{**}) = q_2^{**}$ will not necessarily satisfy Eq. (14.1) and isn't necessarily a Nash equilibrium strategy (the *constant* function $\gamma_2 \equiv q_2^{**}$ does).

We can also show that the payoff for P_1 from the dynamic equilibrium is at least as good as that from the static equilibrium.

$$\begin{aligned} U_1(q_1^*, R_2(q_1^*)) &= \max_{q_1} U_1(q_1, R_2(q_1)) \\ &\geq U_1(q_1^{**}, R_2(q_1^{**})) \\ &= U_1(q_1^{**}, q_2^{**}) \end{aligned}$$

14.2.2 Interpretation

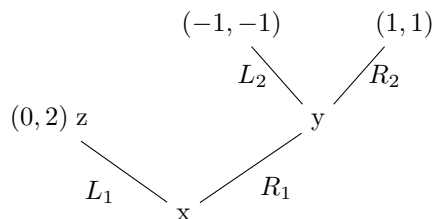
We can interpret the static equilibrium as if P_2 is disregarding what P_1 is doing and is fixated on playing q_2^{**} . This is as if P_2 is issuing P_1 a threat – a threat to play irrationally at a certain node. It is irrational in the sense if P_1 had played anything other than q_1^{**} then playing q_2^{**} would not be optimal any more for P_2 . But this induces P_1 to play q_1^{**} in which case, q_2^{**} is the best response. So, q_2^{**} is irrational only at certain 'meta situations' which actually do not arise!

In essence, there are two Nash equilibria: 1) one which exploits the information structure of the game – dynamic equilibrium; and the 2) other equilibrium which is of the static game.

It is also interesting to observe that P_1 will gain in going from a static equilibrium to a dynamic one – P_1 has an advantage in playing first. But there's also a possibility of a trick when P_2 plays a seemingly irrational strategy.

14.3 Another example

Players P_1 and P_2 play the following game with P_1 making the first move starting at node x. If P_1 plays L_1 , the game ends. Else if P_1 plays R_1 , P_2 has to move next at node y.



In the following description, γ_j^i denotes the j^{th} strategy of i^{th} player. Let us enumerate available strategies for P_1 :

$$\begin{aligned} \gamma_1^1 &\equiv L_1 \\ \gamma_2^1 &\equiv R_1 \end{aligned}$$

Let DN denotes the the action of doing nothing when P_2 is at node z, then $\gamma_2 : \{y, z\} \rightarrow \{L_2, R_2, DN\}$ will be P_2 's strategy satisfying:

$$\gamma_2(y) \in \{L_2, R_2\}$$

$$\gamma_2(z) = DN$$

Thus,

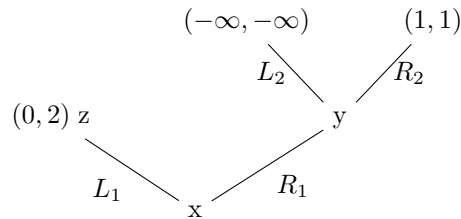
$$\gamma_1^2 = \begin{cases} L_2 & \text{at } y \\ DN & \text{at } z \end{cases}$$

$$\gamma_2^2 = \begin{cases} R_2 & \text{at } y \\ DN & \text{at } z \end{cases}$$

are the two strategies for P_2 . It is left as an exercise for the motivated reader to check that (γ_1^1, γ_1^2) and (γ_2^1, γ_2^2) are the Nash equilibria for the above dynamic game.

Here we obtain (γ_2^1, γ_2^2) by the dynamic analysis and the other equilibrium (γ_1^1, γ_1^2) which can be interpreted similar to the above discussion – P_2 issues a threat to P_1 of playing irrationally.

An interesting variant of the above game is the following:



Here if P_2 issues a threat of playing L_2 , ie. irrationally, then P_1 must adjust to the equilibrium $(0, 2)$. Suppose P_1 and P_2 were nuclear armed countries, then the use of nuclear weapons by P_2 is destructive for both P_1 and P_2 . Thus, the threat of P_2 using nuclear warfare forces P_1 to play L_1 , thus reaching the equilibrium $(0, 2)$. This is the essence of the doctrine of Mutually Assured Destruction (MAD).